

## Theoretical 2: Solution

### Relativistic Correction on GPS Satellite

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#### Part A. Single accelerated particle

1. The equation of motion is given by

$$F = \frac{d}{dt}(\gamma mv) \quad (1)$$

$$= \frac{mc\dot{\beta}}{(1 - \beta^2)^{\frac{3}{2}}}$$

$$F = \gamma^3 ma, \quad (2)$$

where  $\gamma = \frac{1}{\sqrt{1 - \beta^2}}$  and  $\beta = \frac{v}{c}$ . So the acceleration is given by

$$a = \frac{F}{\gamma^3 m}. \quad (3)$$

2. Eq.(3) can be rewritten as

$$c \frac{d\beta}{dt} = \frac{F}{\gamma^3 m}$$

$$\int_0^\beta \frac{d\beta}{(1 - \beta^2)^{\frac{3}{2}}} = \frac{F}{mc} \int_0^t dt$$

$$\frac{\beta}{\sqrt{1 - \beta^2}} = \frac{Ft}{mc} \quad (4)$$

$$\beta = \frac{\frac{Ft}{mc}}{\sqrt{1 + \left(\frac{Ft}{mc}\right)^2}}. \quad (5)$$

3. Using Eq.(5), we get

$$\int_0^x dx = \int_0^t \frac{Ftdt}{m\sqrt{1 + \left(\frac{Ft}{mc}\right)^2}}$$

$$x = \frac{mc^2}{F} \left( \sqrt{1 + \left(\frac{Ft}{mc}\right)^2} - 1 \right). \quad (6)$$

4. Consider the following systems, a frame S' is moving with respect to another frame S, with velocity  $u$  in the  $x$  direction. If a particle is moving in the S' frame with velocity  $v'$  also in  $x$  direction, then the particle velocity in the S frame is given by

$$v = \frac{u + v'}{1 + \frac{uv'}{c^2}}. \quad (7)$$

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If the particles velocity changes with respect to the S' frame, then the velocity in the S frame is also change according to

$$dv = \frac{dv'}{1 + \frac{uv'}{c^2}} - \frac{u + v'}{(1 + \frac{uv'}{c^2})^2} \frac{udv'}{c^2}$$

$$dv = \frac{1}{\gamma^2} \frac{dv'}{(1 + \frac{uv'}{c^2})^2}. \quad (8)$$

The time in the S' frame is  $t'$ , so the time in the S frame is given by

$$t = \gamma \left( t' + \frac{ux'}{c^2} \right), \quad (9)$$

so the time change in the S' frame will give a time change in the S frame as follow

$$dt = \gamma dt' \left( 1 + \frac{uv'}{c^2} \right). \quad (10)$$

The acceleration in the S frame is given by

$$a = \frac{dv}{dt} = \frac{a'}{\gamma^3} \frac{1}{(1 + \frac{uv'}{c^2})^3}. \quad (11)$$

If the S' frame is the proper frame, then by definition the velocity  $v' = 0$ . Substitute this to the last equation, we get

$$a = \frac{a'}{\gamma^3}. \quad (12)$$

Combining Eq.(3) and Eq.(12), we get

$$a' = \frac{F}{m} \equiv g. \quad (13)$$

5. Eq.(3) can also be rewritten as

$$c \frac{d\beta}{\gamma d\tau} = \frac{g}{\gamma^3} \quad (14)$$

$$\int_0^\beta \frac{d\beta}{1 - \beta^2} = \frac{g}{c} \int_0^\tau d\tau$$

$$\ln \left( \frac{1}{\sqrt{1 - \beta^2}} + \frac{\beta}{\sqrt{1 - \beta^2}} \right) = \frac{g\tau}{c} \quad (15)$$

$$\sqrt{\frac{1 + \beta}{1 - \beta}} = e^{\frac{g\tau}{c}}$$

$$\beta \left( e^{\frac{g\tau}{c}} + e^{-\frac{g\tau}{c}} \right) = e^{\frac{g\tau}{c}} - e^{-\frac{g\tau}{c}}$$

$$\beta = \tanh \frac{g\tau}{c}. \quad (16)$$

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6. The time dilation relation is

$$dt = \gamma d\tau. \quad (17)$$

From eq.(16), we have

$$\gamma = \frac{1}{\sqrt{1 - \beta^2}} = \cosh \frac{g\tau}{c}. \quad (18)$$

Combining this equations, we get

$$\begin{aligned} \int_0^t dt &= \int_0^\tau d\tau \cosh \frac{g\tau}{c} \\ t &= \frac{c}{g} \sinh \frac{g\tau}{c}. \end{aligned} \quad (19)$$

#### Part B. Flight Time

1. When the clock in the origin time is equal to  $t_0$ , it emits a signal that contain the information of its time. This signal will arrive at the particle at time  $t$ , while the particle position is at  $x(t)$ . We have

$$c(t - t_0) = x(t) \quad (20)$$

$$t - t_0 = \frac{c}{g} \left( \sqrt{1 + \left( \frac{gt}{c} \right)^2} - 1 \right)$$

$$t = \frac{t_0}{2} \frac{2 - \frac{gt_0}{c}}{1 - \frac{gt_0}{c}}. \quad (21)$$

When the information arrive at the particle, the particle's clock has a reading according to eq.(19). So we get

$$\begin{aligned} \frac{c}{g} \sinh \frac{g\tau}{c} &= \frac{t_0}{2} \frac{2 - \frac{gt_0}{c}}{1 - \frac{gt_0}{c}} \\ 0 &= \frac{1}{2} \left( \frac{gt_0}{c} \right)^2 - \frac{gt_0}{c} \left( 1 + \sinh \frac{g\tau}{c} \right) + \sinh \frac{g\tau}{c} \\ \frac{gt_0}{c} &= 1 + \sinh \frac{g\tau}{c} \pm \cosh \frac{g\tau}{c}. \end{aligned} \quad (22)$$

Using initial condition  $t = 0$  when  $\tau = 0$ , we choose the negative sign

$$\begin{aligned} \frac{gt_0}{c} &= 1 + \sinh \frac{g\tau}{c} - \cosh \frac{g\tau}{c} \\ t_0 &= \frac{c}{g} \left( 1 - e^{-\frac{g\tau}{c}} \right). \end{aligned} \quad (23)$$

As  $\tau \rightarrow \infty$ ,  $t_0 = \frac{c}{g}$ . So the clock reading will freeze at this value.

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2. When the particles clock has a reading  $\tau_0$ , its position is given by eq.(6), and the time  $t_0$  is given by eq.(19). Combining this two equation, we get

$$x = \frac{c^2}{g} \left( \sqrt{1 + \sinh^2 \frac{g\tau_0}{c}} - 1 \right). \quad (24)$$

The particle's clock reading is then sent to the observer at the origin. The total time needed for the information to arrive is given by

$$\begin{aligned} t &= \frac{c}{g} \sinh \frac{g\tau_0}{c} + \frac{x}{c} \\ &= \frac{c}{g} \left( \sinh \frac{g\tau_0}{c} + \cosh \frac{g\tau_0}{c} - 1 \right) \end{aligned} \quad (25)$$

$$t = \frac{c}{g} \left( e^{\frac{g\tau_0}{c}} - 1 \right) \quad (26)$$

$$\tau_0 = \frac{c}{g} \ln \left( \frac{gt}{c} + 1 \right). \quad (27)$$

The time will not freeze.

#### Part C. Minkowski Diagram

1. The figure below show the setting of the problem.

The line AB represents the stick with proper length equal  $L$  in the S frame.

The length AB is equal to  $\sqrt{\frac{1-\beta^2}{1+\beta^2}}L$  in the S' frame.

The stick length in the S' frame is represented by the line AC

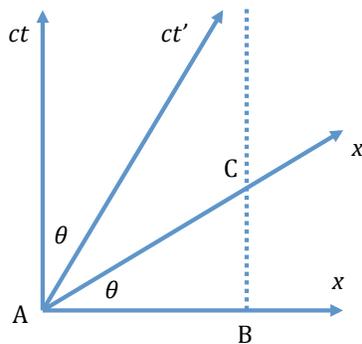


Figure 1: Minkowski Diagram

$$AC = \frac{AB}{\cos \theta} = \sqrt{1 - \beta^2}L. \quad (28)$$

2. The position of the particle is given by eq.(6).

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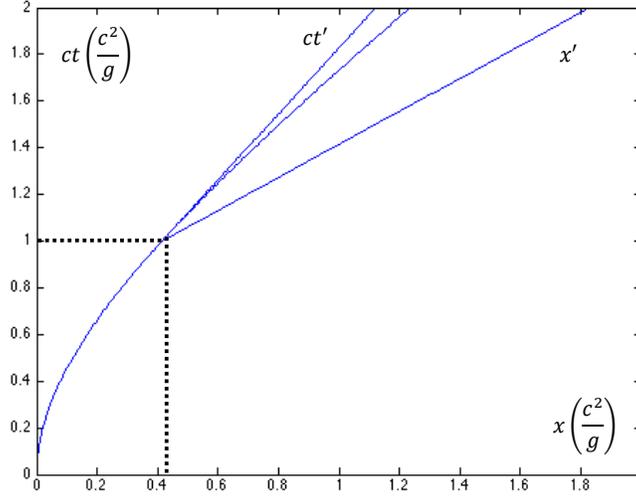


Figure 2: Minkowski Diagram

#### Part D. Two Accelerated Particles

1.  $\tau_B = \tau_A$ .
2. From the diagram, we have

$$\tan \theta = \beta = \frac{ct_2 - ct_1}{x_2 - x_1}. \quad (29)$$

Using eq.(6), and eq.(19) along with the initial condition, we get

$$x_1 = \frac{c^2}{g} \left( \cosh \frac{g\tau_1}{c} - 1 \right), \quad (30)$$

$$x_2 = \frac{c^2}{g} \left( \cosh \frac{g\tau_2}{c} - 1 \right) + L. \quad (31)$$

Using eq.(16), eq.(19), eq.(30) and eq.(31), we obtain

$$\begin{aligned} \tanh \frac{g\tau_1}{c} &= \frac{c \left( \frac{c}{g} \sinh \frac{g\tau_2}{c} - \frac{c}{g} \sinh \frac{g\tau_1}{c} \right)}{L + \frac{c^2}{g} \left( \cosh \frac{g\tau_2}{c} - 1 \right) - \frac{c^2}{g} \left( \cosh \frac{g\tau_1}{c} - 1 \right)} \\ &= \frac{\sinh \frac{g\tau_2}{c} - \sinh \frac{g\tau_1}{c}}{\frac{gL}{c^2} + \cosh \frac{g\tau_2}{c} - \cosh \frac{g\tau_1}{c}} \\ \frac{gL}{c^2} \sinh \frac{g\tau_1}{c} &= \sinh \frac{g\tau_2}{c} \cosh \frac{g\tau_1}{c} - \cosh \frac{g\tau_2}{c} \sinh \frac{g\tau_1}{c} \\ \frac{gL}{c^2} \sinh \frac{g\tau_1}{c} &= \sinh \frac{g}{c} (\tau_2 - \tau_1). \end{aligned} \quad (32)$$

So  $C_1 = \frac{gL}{c^2}$ .

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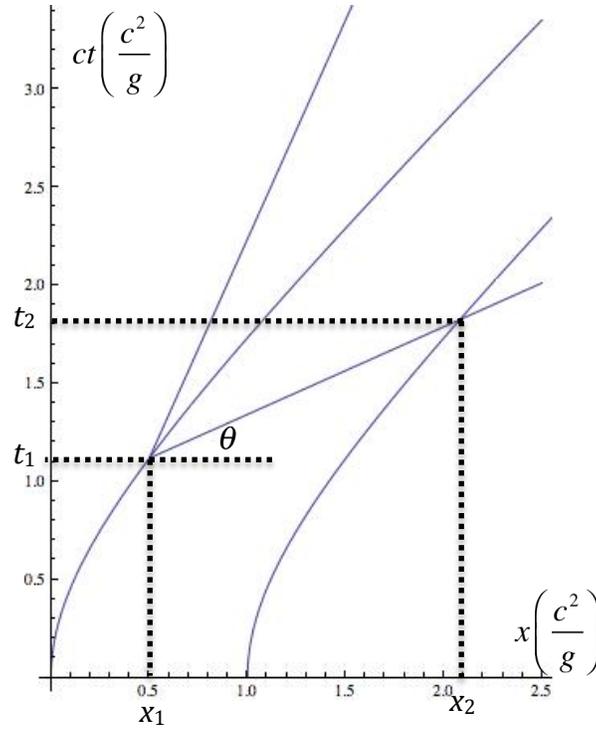


Figure 3: Minkowski Diagram for two particles

3. From the length contraction, we have

$$L' = \frac{x_2 - x_1}{\gamma_1} \quad (33)$$

$$\frac{dL'}{d\tau_1} = \left( \frac{dx_2}{d\tau_2} \frac{d\tau_2}{d\tau_1} - \frac{dx_1}{d\tau_1} \right) \frac{1}{\gamma_1} - \frac{x_2 - x_1}{\gamma_1^2} \frac{d\gamma_1}{d\tau_1}. \quad (34)$$

Take derivative of eq.(30), eq.(31) and eq.(32), we get

$$\frac{dx_1}{d\tau_1} = c \sinh \frac{g\tau_1}{c}, \quad (35)$$

$$\frac{dx_2}{d\tau_2} = c \sinh \frac{g\tau_2}{c}, \quad (36)$$

$$\frac{gL}{c^2} \cosh \frac{g\tau_1}{c} = \cosh \frac{g}{c} (\tau_2 - \tau_1) \left( \frac{d\tau_2}{d\tau_1} - 1 \right). \quad (37)$$

The last equation can be rearrange to get

$$\frac{d\tau_2}{d\tau_1} = \frac{\frac{gL}{c^2} \cosh \frac{g\tau_1}{c}}{\cosh \frac{g}{c} (\tau_2 - \tau_1)} + 1. \quad (38)$$

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From eq.(29), we have

$$x_2 - x_1 = \frac{c(t_2 - t_1)}{\beta_1} = \frac{c}{\tanh \frac{g\tau_1}{c}} \left( \frac{c}{g} \sinh \frac{g\tau_2}{c} - \frac{c}{g} \sinh \frac{g\tau_1}{c} \right). \quad (39)$$

Combining all these equations, we get

$$\begin{aligned} \frac{dL_1}{d\tau_1} &= \left( c \sinh \frac{g\tau_2}{c} \frac{\frac{gL}{c^2} \cosh \frac{g\tau_1}{c}}{\cosh \frac{g}{c} (\tau_2 - \tau_1)} + c \sinh \frac{g\tau_2}{c} - c \sinh \frac{g\tau_1}{c} \right) \frac{1}{\cosh \frac{g\tau_1}{c}} \\ &\quad - \frac{c^2}{g} \left( \sinh \frac{g\tau_2}{c} - \sinh \frac{g\tau_1}{c} \right) \frac{1}{\tanh \frac{g\tau_1}{c}} \frac{1}{\cosh^2 \frac{g\tau_1}{c}} \frac{g}{c} \sinh \frac{g\tau_1}{c} \\ \frac{dL_1}{d\tau_1} &= \frac{gL}{c} \frac{\sinh \frac{g\tau_2}{c}}{\cosh \frac{g}{c} (\tau_2 - \tau_1)}. \end{aligned} \quad (40)$$

So  $C_2 = \frac{gL}{c}$ .

#### Part E. Uniformly Accelerated Frame

- Distance from a certain point  $x_p$  according to the particle's frame is

$$L' = \frac{x - x_p}{\gamma} \quad (41)$$

$$L' = \frac{\frac{c^2}{g_1} (\cosh \frac{g_1\tau}{c} - 1) - x_p}{\cosh \frac{g_1\tau}{c}}$$

$$L' = \frac{c^2}{g_1} - \frac{\frac{c^2}{g_1} + x_p}{\cosh \frac{g_1\tau}{c}}. \quad (42)$$

For  $L'$  equal constant, we need  $x_p = -\frac{c^2}{g_1}$ .

- First method:** If the distance in the S' frame is constant =  $L$ , then in the S frame the length is

$$L_s = L \sqrt{\frac{1 + \beta^2}{1 - \beta^2}}. \quad (43)$$

So the position of the second particle is

$$x_2 = x_1 + L_s \cos \theta \quad (44)$$

$$= \frac{c^2}{g_1} \left( \sqrt{1 + \left( \frac{g_1 t_1}{c} \right)^2} - 1 \right) + L \sqrt{1 + \left( \frac{g_1 t_1}{c} \right)^2}$$

$$x_2 = \left( \frac{c^2}{g_1} + L \right) \sqrt{1 + \left( \frac{g_1 t_1}{c} \right)^2} - \frac{c^2}{g_1}. \quad (45)$$

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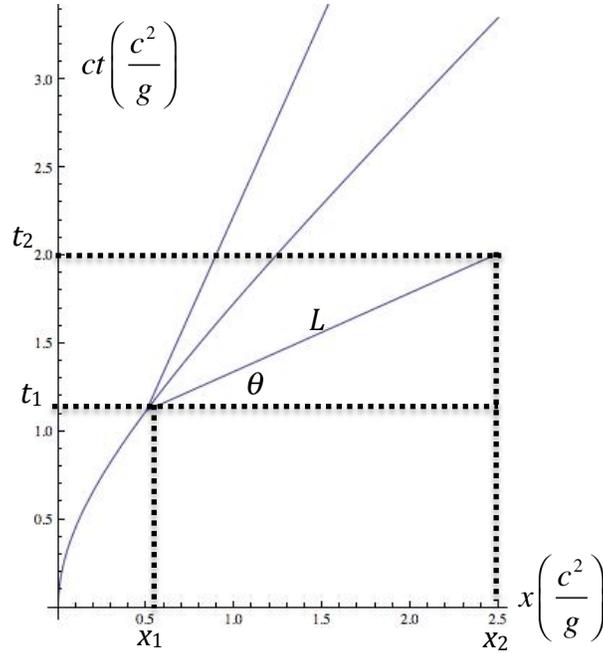


Figure 4: Minkowski Diagram for two particles

The time of the second particle is

$$ct_2 = ct_1 + L_s \sin \theta \quad (46)$$

$$= ct_1 + L \sqrt{\frac{1 + \beta^2}{1 - \beta^2}} \frac{\beta}{\sqrt{1 + \beta^2}}$$

$$ct_2 = t_1 \left( c + \frac{g_1 L}{c} \right). \quad (47)$$

Substitute eq.(47) to eq.(45) to get

$$x_2 = \left( \frac{c^2}{g_1} + L \right) \sqrt{1 + \left( \frac{g_1}{c} \frac{t_2}{1 + \frac{g_1 L}{c^2}} \right)^2} - \frac{c^2}{g_1}$$

$$x_2 = \left( \frac{c^2}{g_1} + L \right) \sqrt{1 + \left( \frac{g_1}{1 + \frac{g_1 L}{c^2}} \frac{t_2}{c} \right)^2} - \frac{c^2}{g_1}. \quad (48)$$

From the last equation, we can identify

$$g_2 \equiv \frac{g_1}{1 + \frac{g_1 L}{c^2}}. \quad (49)$$

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As for confirmation, we can substitute this relation to the second particle position to get

$$x_2 = \frac{c^2}{g_2} \sqrt{1 + \left(\frac{g_2 t_2}{c}\right)^2} - \frac{c^2}{g_1}. \quad (50)$$

**Second method:** In this method, we will choose  $g_2$  such that the special point like the one describe in the question 1 is exactly the same as the similar point for the proper acceleration  $g_1$ .

For first particle, we have  $x_{p1}g_1 = c^2$

For second particle, we have  $(L + x_{p1})g_2 = c^2$

Combining this two equations, we get

$$g_2 = \frac{c^2}{L + \frac{c^2}{g_1}}$$

$$g_2 = \frac{g_1}{1 + \frac{g_1 L}{c^2}}. \quad (51)$$

3. The relation between the time in the two particles is given by eq.(47)

$$t_2 = t_1 \left(1 + \frac{g_1 L}{c^2}\right)$$

$$\frac{c^2}{g_2} \sinh \frac{g_2 \tau_2}{c} = \frac{c^2}{g_1} \sinh \frac{g_1 \tau_1}{c} \left(1 + \frac{g_1 L}{c^2}\right)$$

$$\sinh \frac{g_2 \tau_2}{c} = \sinh \frac{g_1 \tau_1}{c}$$

$$g_2 \tau_2 = g_1 \tau_1 \quad (52)$$

$$\frac{d\tau_2}{d\tau_1} = \frac{g_1}{g_2} = 1 + \frac{g_1 L}{c^2}. \quad (53)$$

#### Part F. Correction for GPS

1. From Newtons Law

$$\frac{GMm}{r^2} = m\omega^2 r \quad (54)$$

$$r = \left(\frac{gR^2 T^2}{4\pi^2}\right)^{\frac{1}{3}} \quad (55)$$

$$r = 2.66 \times 10^7 \text{m.}$$

The velocity is given by

$$v = \omega r = \left(\frac{2\pi g R^2}{T}\right)^{\frac{1}{3}}$$

$$= 3.87 \times 10^3 \text{m/s.} \quad (56)$$

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2. The general relativity effect is

$$\frac{d\tau_g}{dt} = 1 + \frac{\Delta U}{mc^2} \quad (57)$$

$$\frac{d\tau_g}{dt} = 1 + \frac{gR^2}{c^2} \frac{R-r}{Rr}. \quad (58)$$

After one day, the difference is

$$\begin{aligned} \Delta\tau_g &= \frac{gR^2}{c^2} \frac{R-r}{Rr} \Delta T \\ &= 4.55 \times 10^{-5} \text{s}. \end{aligned} \quad (59)$$

The special relativity effect is

$$\frac{d\tau_s}{dt} = \sqrt{1 - \frac{v^2}{c^2}} \quad (60)$$

$$\begin{aligned} &= \sqrt{1 - \left( \left( \frac{2\pi gR^2}{T} \right)^{\frac{2}{3}} \right) \frac{1}{c^2}} \\ &\approx 1 - \frac{1}{2} \left( \left( \frac{2\pi gR^2}{T} \right)^{\frac{2}{3}} \right) \frac{1}{c^2}. \end{aligned} \quad (61)$$

After one day, the difference is

$$\begin{aligned} \Delta\tau_s &= -\frac{1}{2} \left( \left( \frac{2\pi gR^2}{T} \right)^{\frac{2}{3}} \right) \frac{1}{c^2} \Delta T \\ &= -7.18 \times 10^{-6} \text{s}. \end{aligned} \quad (62)$$

The satellite's clock is faster with total  $\Delta\tau = \Delta\tau_g + \Delta\tau_s = 3.83 \times 10^{-5} \text{s}$ .

3.  $\Delta L = c\Delta\tau = 1.15 \times 10^4 \text{m} = 11.5 \text{km}$ .